

CPSC 314

Computer Graphics

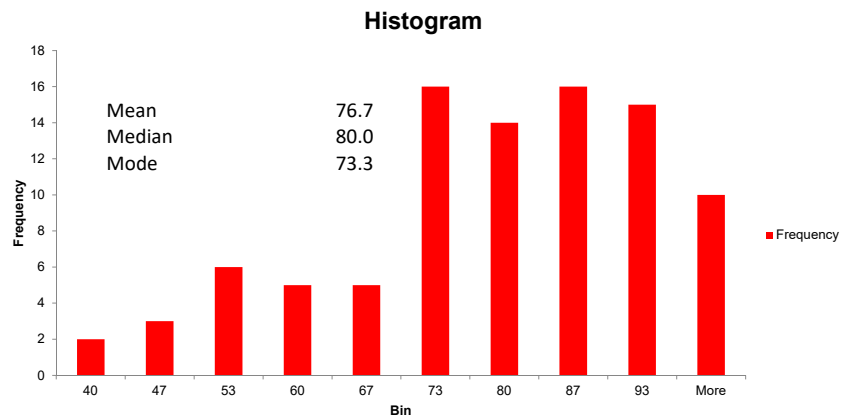
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Frames in Graphics

Announcements

- Quiz 1 handback now available.
- Assignment 2 available soon, possibly this weekend.
- Homework for today:
 - Read textbook Chapter 5

Quiz 1 stats



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Quiz 1 handback

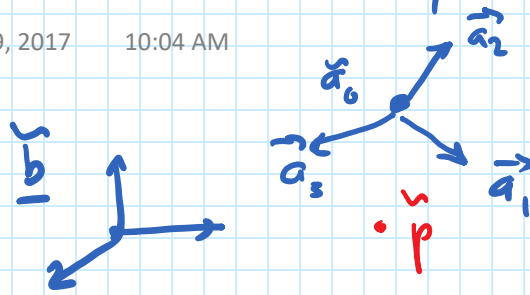
- Scanned exam books are now available here
<https://www.ugrad.cs.ubc.ca/~cs314/handback/>
Login with your cs id
- Grades will be uploaded to Connect in a few days

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Frames in Graphics (chap. 5)

September 29, 2017

10:04 AM



Basic Recipe

$$\tilde{p} = \tilde{b} \bar{p}_b = \tilde{a} \bar{p}_a = \tilde{b} \bar{A} \bar{p}_a$$

$$\tilde{b} \bar{A}$$

The point is the same, regardless of the frame
convert coordinates into the same frame
before you compute

Currency analogy of a frame

$$\text{\$}25 = \text{\pounds}20 = \text{\$A}20$$

§ Classic frames in graphics

World fr \tilde{w}
synonym: Scene

Everything is defined w.r.t. \tilde{w}
(ultimately)

Object frame \tilde{o}
syn: model frame

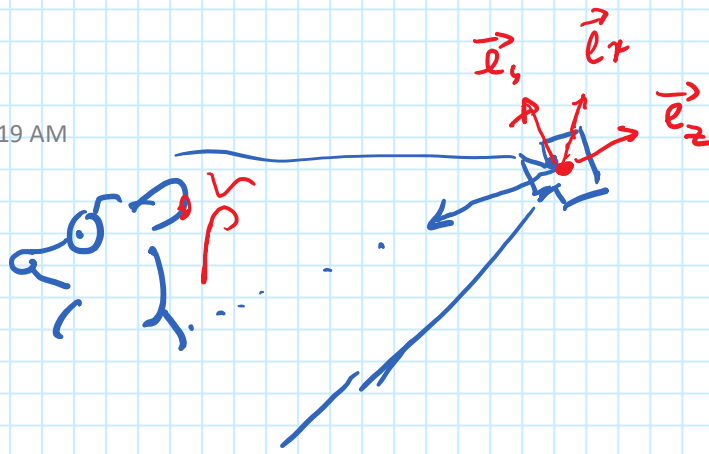
Fixed to an object. Positions
are defined w.r.t. \tilde{o}

book's term
Eye frame \tilde{e}

$\tilde{o} = \tilde{w} \bar{O}$
Fixed to the eye/camera
convention in graphics:

View frame
or
Camera frame

looking along $-z$
y-axis is "up" $\tilde{e} = \tilde{w} \bar{E}$



When it is clear which frame we are using we'll simplify notation as follows

Matrix	4x1 column (Point, vector)
O	p
E	v
Just caps	lower case

still use the decorations for frames, points, vectors

$$\tilde{p} = \tilde{o} p_o = \tilde{w} o p_o$$

object coords.

$$\tilde{p} = \tilde{e} p_e = \tilde{w} E p_e$$

eye-coord coords

so

$$o p_o = E p_e$$

$$p_e = \tilde{E}^{-1} o p_o$$

View Matrix Model Matrix
 Model View

How to transform object about an auxiliary frame

Read Sec. 5.2 of book

want to apply a transform about

$$\underline{\hat{m}} = \underline{\hat{w}} M$$

$$\underline{\hat{p}} = \underline{\hat{m}} P_m, \text{ convert to world frame and then back}$$

To be continued...